

A Fokker-Planck description of dense flows

Mohsen Sadr

Supervisors: Dr. Hossein Gorji
Prof. Manuel Torrilhon

Computational Engineering Science, Mathematics Division
RWTH Aachen University

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1 Introduction

- Motivation

2 Dense Gases

- Enskog Equation
- Fokker-Planck model
- Validation studies

3 Conclusion

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Why this topic?

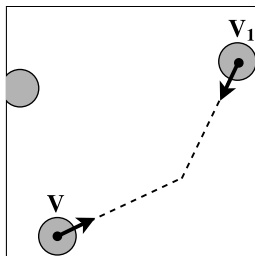
- We want
an efficient kinetic model that can describe non-equilibrium dilute, dense gases and if possible, phase transition to liquids.

Why this topic?

- We want
an efficient kinetic model that can describe non-equilibrium dilute, dense gases and if possible, phase transition to liquids.
- **DSMC** based methods (ESMC, ...) become **too expensive** at high densities.
- We need an accurate mathematical model whose **computational cost** has **no correlation with density**.
- Applications: unconventional gas reservoirs, high pressure shock tubes, Sonoluminescence, and interface of liquid-vapor at supercritical pressures.

Collision in dilute .vs. dense gases

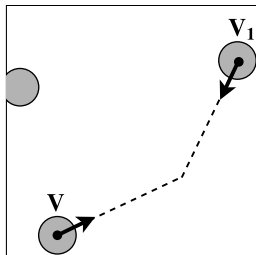
Dilute



Point particle:
Boltzmann collision operator

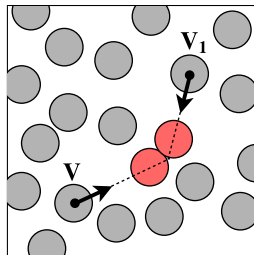
Collision in dilute .vs. dense gases

Dilute



Point particle:
Boltzmann collision operator

Dense



Particles with Sutherland potential:
Enskog collision operator
+ **attraction**.

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Enskog equation¹

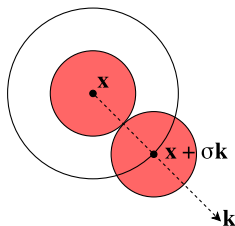
Enskog modified Boltzmann equation in order to include dense effects

$$\frac{\partial \mathcal{F}}{\partial t} + \frac{\partial(\mathcal{F} V_i)}{\partial x_i} = S^{\text{Ensk}}, \quad (2.1)$$

where

$$S^{\text{Ensk}} = \int_{\mathbb{R}^3} \int_0^{2\pi} \int_0^{+\infty} \left[Y(\mathbf{x} + \frac{1}{2}\sigma\hat{\mathbf{k}}) \mathcal{F}(\mathbf{V}^*, \mathbf{x}) \mathcal{F}(\mathbf{V}_1^*, \mathbf{x} + \sigma\hat{\mathbf{k}}) \right. \\ \left. - Y(\mathbf{x} - \frac{1}{2}\sigma\hat{\mathbf{k}}) \mathcal{F}(\mathbf{V}, \mathbf{x}) \mathcal{F}(\mathbf{V}_1, \mathbf{x} - \sigma\hat{\mathbf{k}}) \right] g \hat{b} d\hat{b} d\hat{e} d^3\mathbf{V}_1. \quad (2.2)$$

- \hat{b} , \hat{e} and $\hat{\mathbf{k}}$ specify collision cross section.
- σ : effective diameter of particles.
- Y : pair correlation function.
- $*$: post-collision state.



¹ see Chapman, S., & Cowling, T. (1953) and Hirschfelder, J. *et al.* (1963).

Modifying DSMC (ESMC² and Frezzotti's algorithm³) such that:

- Collision rate is increased by the factor Y , i.e.

$$\omega_{ij}/\Delta t = 4\pi\sigma^2(\mathbf{k}\cdot\mathbf{g}_{ij})Y(\mathbf{x} + \sigma/2\hat{\mathbf{k}})n_J \quad (2.3)$$

- Colliding pair is selected from cells that enclose \mathbf{x} and $\mathbf{x} + \sigma\hat{\mathbf{k}}$.

² see Montanero, J. M., & Santos, A., Physical Review E 54, no. 1 (1996): 438.

³ see Frezzotti, A. Physics of Fluids 9, no. 5 (1997): 1329-1335.

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Problem

Computational complexity of DSMC-based methods increases with density since collision rate of HS is $\omega_{ij}/\Delta t = 4\pi\sigma^2(\mathbf{k}\cdot\mathbf{g}_{ij})Y(\mathbf{x} + \sigma/2\hat{\mathbf{k}})n_J$.

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Fokker-Planck model

Consider an Itô process

$$d\mathbf{p} = \tilde{\mathbf{A}}dt + \lambda d\mathbf{W}, \quad (2.4)$$

where \mathbf{W} is a Wiener process. Itô calculus provides us the equivalent Fokker-Planck equation⁴

$$\frac{\partial \mathcal{F}}{\partial t} + \frac{\partial(\mathcal{F}V_i)}{\partial x_i} = -\frac{\partial(\mathcal{F}A_i)}{\partial V_i} + \frac{1}{2} \frac{\partial^2}{\partial V_i \partial V_j} (D_{ik} D_{kj} \mathcal{F}). \quad (2.5)$$

Drift and diffusion

\mathbf{A} and \mathbf{D} are called drift and diffusion coefficients, respectively. They are set to give an approximation of a generic collision operator.

⁴ see Gardiner, C. W. (1996).

Homogeneous relaxation rates of Enskog equation

- Let us write Enskog operator using the decomposition

$$S^{\text{Ensk}} = Y(\mathbf{x})S^{\text{Boltz}} + S_{\phi} \quad (2.6)$$

where S_{ϕ} includes all spatial dependency of \mathcal{F} and Y in \mathbf{x} .

- Relaxation rates of shear stress and heat fluxes then become

$$\left. \frac{\partial \pi_{ij}}{\partial t} \right|_{\text{coll}} = -Y \frac{p}{\mu^{\text{kin}}} \pi_{ij} \quad (2.7)$$

$$\text{and} \quad \left. \frac{\partial q_i}{\partial t} \right|_{\text{coll}} = -Y \frac{2}{3} \frac{p}{\mu^{\text{kin}}} q_i . \quad (2.8)$$

- Drift \mathbf{A} and diffusion \mathbf{D} can be modelled by a cubic FP model proposed by Gorji *et al.*⁵ with modifications for dense gases.

⁵Gorji, M. H. and Torrilhon, M. and Jenny, P., Journal of fluid mechanics 680 (2011): 574-601.

Conservation equations of Enskog equation

- Taking velocity moment $\psi \in \{1, V_j, V_j V_j/2\}$ of expanded Enskog equation leads to

$$\int_{\mathbb{R}^3} \psi \left(\frac{\partial \mathcal{F}}{\partial t} + V_i \frac{\partial \mathcal{F}}{\partial x_i} \right) d^3 \mathbf{V} = - \frac{\partial \Psi_i^\phi}{\partial x_i}. \quad (2.9)$$

where Ψ^ϕ is called collisional transfer and is defined by

$$\begin{aligned} \Psi_i^\phi = & \underbrace{\frac{Y\sigma}{2} \int \int \int \int (\psi^* - \psi) \mathcal{F} \mathcal{F}_1 k_i g \hat{b} d \hat{b} d \hat{e} d^3 \mathbf{V}_1 d^3 \mathbf{V}}_{I_1} \\ & + \underbrace{\frac{Y\sigma^2}{4} \int \int \int \int (\psi^* - \psi) \mathcal{F} \mathcal{F}_1 \frac{\partial}{\partial x_j} \ln\left(\frac{\mathcal{F}}{\mathcal{F}_1}\right) k_i k_j g \hat{b} d \hat{b} d \hat{e} d^3 \mathbf{V}_1 d^3 \mathbf{V}}_{I_2} \\ & + \dots \end{aligned} \quad (2.10)$$

- Unlike Boltzmann, moments of Enskog operator for momentum and energy do not vanish! \rightarrow **collisional transfer**

- Assuming Maxwellian \mathcal{F} in $l_2(\psi)$ and ignoring higher order terms

$$p^{\text{tot}} = \underbrace{(1 + nbY)nkT}_{=l_1} - \underbrace{w \frac{\partial U_k}{\partial x_k}}_{\approx l_2}, \quad (2.11)$$

$$\pi_{ij}^{\text{tot}} = \underbrace{(1 + 2nbY/5)\pi_{ij}}_{=l_1} - \underbrace{(5w/6) \frac{\partial U_{\langle i}}{\partial x_{j \rangle}}}_{\approx l_2} \quad (2.12)$$

and

$$q_i^{\text{tot}} = \underbrace{(1 + 3nbY/5)q_i}_{=l_1} - \underbrace{c_v w \frac{\partial T}{\partial x_i}}_{\approx l_2} \quad (2.13)$$

with $w = (nb)^2 Y \sqrt{mkT} / (\pi^{3/2} \sigma^2)$ being bulk viscosity.

- We use these expressions to correct total pressure tensor and total heat fluxes in FP of dense gases.

- Collisional transfer promotes idea of extra streaming

$$\frac{\partial \mathcal{F}}{\partial t} + \frac{\partial(\mathcal{F}V_i)}{\partial x_i} = -\frac{\partial(\mathcal{F}A_i)}{\partial V_i} + \frac{1}{2} \frac{\partial^2(D^2\mathcal{F})}{\partial V_j \partial V_j} - \frac{\partial(\mathcal{F}\hat{A}_i)}{\partial x_i} . \quad (2.14)$$

- What is $\hat{\mathbf{A}}$?

Answer: $\hat{\mathbf{A}}$ is a spatial drift which should be set such that moments of FP matches moments of Enskog, i.e. provides correction to total pressure tensor and heat fluxes.

- In this study, we proposed a cubic model for $\hat{\mathbf{A}}$, i.e.

$$\hat{A}_i = \hat{c}_{ij}v'_j + \hat{\gamma}_i \left(v'_j v'_j - \frac{3kT}{m} \right) + \hat{\Lambda} \left(v'_i v'_j v'_j - \frac{2q_i}{\rho} \right) \quad (2.15)$$

where $\hat{\Lambda} = -\epsilon n b Y / (kT/m)$ is set to avoid instabilities of SDEs.

Cubic FP: conservation equations

- Mass conservation:

$$\frac{\partial \rho}{\partial t} + \frac{\partial(\rho U_i)}{\partial x_i} = 0 . \quad (2.16)$$

- Momentum conservation:

$$\begin{aligned} \frac{\partial}{\partial t}(\rho U_i) + \frac{\partial}{\partial x_j}(\rho U_i U_j) + \frac{\partial}{\partial x_j}(\pi_{ij} + p\delta_{ij}) \\ + \frac{\partial}{\partial x_j} \int_{\mathbb{R}^3} \hat{A}_j V_i \mathcal{F} d^3 \mathbf{V} = 0 . \end{aligned} \quad (2.17)$$

- Energy conservation:

$$\begin{aligned} \frac{\partial E}{\partial t} + \frac{\partial}{\partial x_i} (E U_i + q_i + p\delta_{ik} U_k + \pi_{ik} U_k) \\ + \frac{1}{2} \frac{\partial}{\partial x_i} \int_{\mathbb{R}^3} \hat{A}_i V_k V_k \mathcal{F} d^3 \mathbf{V} = 0 . \end{aligned} \quad (2.18)$$

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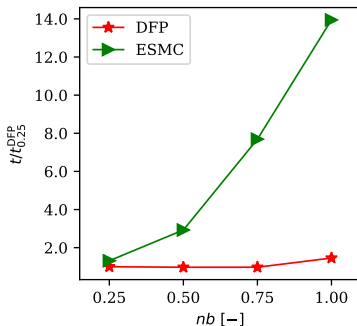
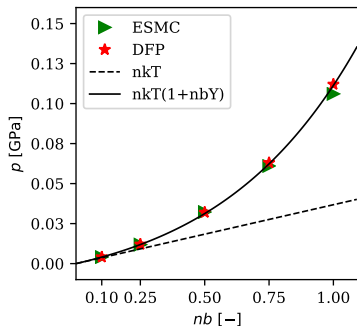
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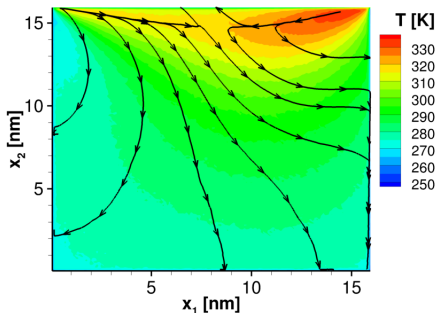
Equilibrium Pressure

- Iso-thermal walls with $T_w = 273\text{ K}$.
- Equilibrium pressure can be calculated based on its fundamental definition.

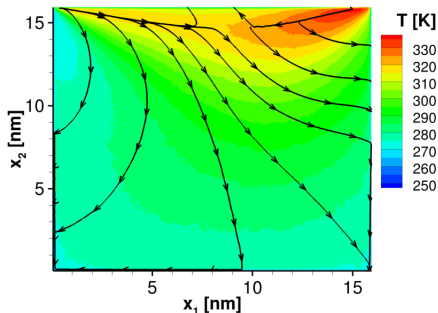


Lid-driven cavity

- Temperature contours and heat fluxes of the lid-driven cavity flow at $Kn = 0.1$, $nb = 0.1$ and $U_w = 300$ m/s.



(a) FP







(b) ESMC

- We proposed a Fokker-Planck model suitable for dense gases.
- Dense gas effects were captured by introducing a drift in physical space.
- Several examples showed the accuracy of model in capturing total pressure, shear stress and heat fluxes.
- Future studies:
 - Obtaining higher order approximation of collisional transfer.
 - Including attractive part of molecular potential.

Thanks for your attention.

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- Motivation
- Kinetic Theory
- Monte-Carlo Methods
- Review: Fokker-Planck model for ideal gas

5 FP model for dense gas

- Investigating Enskog operator
- Modification in Evolution of Velocity
- Modification in Evolution of Position
- Reduction to SDEs
- Numerical Scheme

6 Validation Studies

- Setup
- Equilibrium Pressure
- Couette Flow
- Fourier Flow

7 Conclusion and Outlooks

Why this topic?

- We want
an efficient model that can describe non-equilibrium dilute, dense gases and if possible, liquid.
- **DSMC** based methods, such as ESMC and CBA, are **too expensive**.
- Since collisions are not explicitly calculated in **FP model**, it is shown to be **more efficient** than DSMC based methods as Knudsen number decreases which encourages us to extend it for dense gases as well.
- We need a accurate mathematical model that its **computational cost** has **no correlation with density**.
- Applications: unconventional gas reservoirs[1], high pressure shock tubes[2], Sonoluminescence[3] and interface of liquid-vapor at supercritical pressures[4, 5, 6].

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- Let us consider the sample space of \mathbf{V} and \mathbf{x} .
- Macroscopic properties can be determined by probability density function $f(\mathbf{V}; \mathbf{x}, t)$, i.e. probability density of finding a particle close to the velocity \mathbf{V} and conditional on $\mathbf{x} - t$.
- Here, velocity distribution function (VDF) $\mathcal{F}(\mathbf{V}, \mathbf{x}, t)$ is employed where

$$\mathcal{F}(\mathbf{V}, \mathbf{x}, t) = \rho(\mathbf{x}, t)f(\mathbf{V}; \mathbf{x}, t), \quad (5.1)$$

- Kinetic Theory provides macroscopic properties as functions of VDF

$$\rho(\mathbf{x}, t) = \int_{R^3} \mathcal{F} d^3\mathbf{V}, \quad (5.2) \quad T = \frac{1}{3nk_b} \int_{R^3} \mathcal{F} v_j' v_j' d^3\mathbf{V}, \quad (5.5)$$

$$\langle \psi(\mathbf{M}) \rangle = \frac{1}{\rho} \int_{R^3} \phi(\mathbf{V}) \mathcal{F} d^3\mathbf{V}, \quad (5.3) \quad \pi_{ij} = \int_{R^3} \mathcal{F} v_i' v_j' d^3\mathbf{V} \text{ and} \quad (5.6)$$

$$U_i = \frac{1}{\rho} \int_{R^3} \mathcal{F} V_i d^3\mathbf{V}, \quad (5.4) \quad q_i = \frac{1}{2} \int_{R^3} \mathcal{F} v_i' v_j' v_j' d^3\mathbf{V}. \quad (5.7)$$

- **If we know evolution of \mathcal{F} , we know future macroscopic states of the system.**
- Generic form of the evolution of distribution function of each particle in non-equilibrium gas

$$\frac{\partial \mathcal{F}}{\partial t} + \frac{\partial(\mathcal{F} V_i)}{\partial x_i} + \frac{\partial(\mathcal{F} G_i)}{\partial V_i} = S_{coll}(\mathcal{F}) . \quad (5.8)$$

- $S_{coll}(\mathcal{F})$ collision operator accounting for the binary collisions among molecules and \mathbf{G} the external force.
- $S_{coll}(\mathcal{F})$ is the Boltzmann operator for dilute gas and the Enskog operator for dense gases.

Enskog operator⁶

- With simple modification to the Boltzmann operator

$$\begin{aligned} S^{Enskog} = \int_{\mathbb{R}^3} \int_0^{2\pi} \int_0^{+\infty} & \left[Y(\mathbf{x} + \frac{1}{2}\sigma\hat{\mathbf{k}}) \mathcal{F}(\mathbf{V}^*, \mathbf{x}) \mathcal{F}(\mathbf{V}_1^*, \mathbf{x} + \sigma\hat{\mathbf{k}}) \right. \\ & \left. - Y(\mathbf{x} - \frac{1}{2}\sigma\hat{\mathbf{k}}) \mathcal{F}(\mathbf{V}, \mathbf{x}) \mathcal{F}(\mathbf{V}_1, \mathbf{x} - \sigma\hat{\mathbf{k}}) \right] g \hat{b} d\hat{b} d\hat{e} d^3\mathbf{V}_1, \end{aligned} \quad (5.9)$$

where

$$Y = 1 + 0.625nb + 0.2869(nb)^2 + 0.115(nb)^3 \text{ and} \quad (5.10)$$

$$b = \frac{2}{3}\pi\sigma^3. \quad (5.11)$$

- Assumptions:

- 1- Volume occupied by the molecules becomes comparable with the whole volume of the gas which leads to the factor Y in collision rate.
- 2- VDF of colliding pair must be in vicinity of each other, exactly σ for HS, for collisions to happen.

⁶ see Chapman and Cowling (1953) [7] and Hirschfelder et al. (1963) [8].

From statistical mechanics, the virial expansion of pressure can be obtained by

$$Z := \frac{p}{nkT} = 1 + B_2 n + B_3 n^2 + B_4 n^3 \dots, \quad (5.12)$$

$$B_N = \frac{1 - N}{N!} \lim_{V \rightarrow 0} V^{-1} \int \dots \int d\mathbf{r}_1 \dots d\mathbf{r}_N V_N, \quad (5.13)$$

$$V_N = \sum \prod_{i < j}^N f_{ij} \quad (5.14)$$

$$\text{and } f_{ij} = \exp(-\phi_{ij}/kT) - 1, \quad (5.15)$$

where ϕ_{ij} is molecular potential between particles i and j .

The factor Y (which comes from virial expansion)

$$Y := \frac{Z - 1}{nb} \quad (5.16)$$

for hard-sphere can be calculated exactly as done by Ree-Hoover [13]

$$Y = 1 + 0.625nb + 0.2869(nb)^2 + 0.115(nb)^3 + \dots \quad (5.17)$$

or approximated by a closed expression as suggested by Carnahan-Starling [14]

$$Y^{CS} = \frac{1 - nb/8}{(1 - nb/4)^3}. \quad (5.18)$$

- Now we know what we want to solve.
- Boltzmann and Enskog equations are difficult to solve directly due to high dimensionality of $\mathcal{F}(\mathbf{V}, \mathbf{x}, t)$.
- Monte-Carlo methods are suggested in literature as an efficient yet accurate alternative compared to direct solution method and moment approach.

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Direct Simulation Monte Carlo (DSMC⁸)

- Positions and velocities are updated in two steps: **streaming** and **collision**.
- Collision involves picking Λ_{coll} couple of particles as candidates

$$\Lambda_{max} = F_N N_C^2 \pi \sigma^2 M_{r,max} \Delta t / V_c. \quad (5.19)$$

- Selected pair collide if

$$M_r / M_{r,max} > r, \quad (5.20)$$

then velocities change such that

$$\mathbf{M}_r^{post} = M_r^{post} (\cos\theta, \sin\theta \cos\phi, \sin\theta \sin\phi)^T, \quad (5.21)$$

$$\phi = 2\pi\alpha_1 \quad \text{and} \quad (5.22)$$

$$\cos\theta = 1 - 2\alpha_2, \quad (5.23)$$

with α_1 and α_2 being uniform random numbers between zero and one.

- DSMC is proven to be consistent with the Boltzmann equation⁷.

⁷Wanger (1992) [15].

⁸Bird (1963) [16].

Consistent Boltzmann Algorithm (CBA⁹)

- **With two modifications in DSMC, one can model dense gas!**
- Collision rate needs to be increased by Y ,

$$\Lambda^{CBA} = Y F_N N_C^2 \pi \sigma^2 M_{r,max} \Delta t / V_C. \quad (5.24)$$

- Additional advection due to diameter effect in streaming

$$\mathbf{d} = \frac{\mathbf{M}_r^* - \mathbf{M}_r}{\|\mathbf{M}_r^* - \mathbf{M}_r\|_2} \sigma, \quad (5.25)$$

$$\mathbf{X}_1 = \mathbf{M}_1 \Delta t + \mathbf{d} \quad \text{and} \quad (5.26)$$

$$\mathbf{X}_2 = \mathbf{M}_2 \Delta t - \mathbf{d}. \quad (5.27)$$

- CBA loses consistency as density increases ($n\sigma^3 > 0.4$).

Complexity of Monte Carlo methods

Complexity scales with $\mathcal{O}(n^2)$, where n is number density.

⁹ see Alexander et al. (1995) [17].

Enskog Simulation Monte-Carlo (ESMC¹⁰)

- ESMC was proposed as an accurate solution to Enskog equation.
- Collision rate is increased by a Y factor, i.e. $\Lambda^{Ensk} = Y\Lambda^{Boltz}$.
- Modification in selection of collision pair:
 - Pick a particle (\mathbf{x}_i) at random.
 - Pick a random direction $\hat{\sigma}$. Then, find the second particle (\mathbf{x}_j) in the cell that $\mathbf{x}_i + \sigma\hat{\sigma}$ exists.
 - Find Y at the mid point and update Λ^{Ensk} if necessary. Calculate $\Gamma = 4\pi\sigma^2(\mathbf{M}_r \cdot \hat{\sigma})Y_{mid}\Delta t$.
 - If $\Gamma/\Gamma_{max} > r$, accept the collision and set $\mathbf{M}_i^* = \mathbf{M}_i - (\mathbf{M}_r \cdot \hat{\sigma})\hat{\sigma}$.

Complexity of Monte Carlo methods

Complexity scales with $\mathcal{O}(n^2)$, where n is number density.

¹⁰ see Montanero and Santos (1996) [9].

- As mentioned, computational cost of DSMC's based methods increases as gas gets denser.
- It is because collision rate increases with density.
- However, FP model does not suffer from this problem.
- Therefore, it is worth expanding FP model for dense gases.

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Review: Fokker-Planck model for ideal gas

- For an Itô process

$$d\mathbf{p} = \tilde{\mathbf{A}}dt + \lambda d\mathbf{W}, \quad (5.28)$$

where \mathbf{W} is a Wiener process and

$$\mathbf{p} = \begin{pmatrix} M_1 \\ M_2 \\ M_3 \\ X_1 \\ X_2 \\ X_3 \end{pmatrix}, \quad \lambda = \begin{pmatrix} D_{11} & D_{12} & D_{13} & 0 & 0 & 0 \\ D_{21} & D_{22} & D_{23} & 0 & 0 & 0 \\ D_{31} & D_{32} & D_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \text{ and } \tilde{\mathbf{A}} = \begin{pmatrix} A_1 \\ A_2 \\ A_3 \\ M_1 \\ M_2 \\ M_3 \end{pmatrix}, \quad (5.29)$$

Itô calculus provides us the equivalent Fokker-Planck equation¹¹

$$\frac{\partial \mathcal{F}}{\partial t} + \frac{\partial(\mathcal{F}V_i)}{\partial x_i} = -\frac{\partial(\mathcal{F}A_i)}{\partial V_i} + \frac{1}{2} \frac{\partial^2}{\partial V_i \partial V_j} (D_{ik} D_{kj} \mathcal{F}). \quad (5.30)$$

Drift and diffusion

A_i and D_{ij} are called drift and diffusion coefficients, respectively. They are set to give stochastics of S_{coll} .

¹¹ see Gardiner (1996) [11].

- Jenny *et al.* (2010) [18] considered a Langevin model

$$A_i = -\frac{1}{\tau} v_i' \quad \text{and} \quad D_{ij} = \sqrt{\frac{2kT}{\tau m}} \delta_{ij}, \quad (5.31)$$

with $\tau = 2\mu^{\text{kin}}/p$.

- Linear model is consistent with the Boltzmann equation up to second velocity moment, i.e. $\psi \in \{1, V_i, V_i V_j\}$.
- It was shown that the linear FP produces inconsistent relaxation rates for shear stress and heat fluxes, consequently inconsistent Prandtl number in hydrodynamic limit.

Review: cubic FP model for ideal gas

- In order to provide consistent relaxation rates, Cubic FP was designed by Gorji *et al.* (2011) [12]

$$A_i = c_{ij}v'_j + \gamma_i \left(v'_j v'_j - \frac{3kT}{m} \right) + \Lambda \left(v'_i v'_j v'_j - \frac{2q_i}{\rho} \right), \quad (5.32)$$

$$D_{ij} = \sqrt{\frac{2kT}{\tau m}} \delta_{ij} \quad \text{and} \quad (5.33)$$

$$\tau = 2\mu^{\text{kin}}/p, \quad (5.34)$$

where coefficients of higher order terms \mathbf{c} and γ are set satisfying homogeneous relaxation rates¹²,

$$\frac{\partial \pi_{ij}}{\partial t} = -\frac{p}{\mu} \pi_{ij} \quad \text{and} \quad (5.35)$$

$$\frac{\partial q_i}{\partial t} = -\frac{2}{3} \frac{p}{\mu} q_i. \quad (5.36)$$

¹² see Truesdell and Muncaster (1980) [19].

Conditions on any S_{coll} describing monatomic dilute gas:

- S_{coll} must conserve mass, momentum and energy i.e. for any $\Psi_{cons} \in \{1, V_i, V_j V_j\}$

$$\int_{\mathbb{R}^3} \Psi_{cons} S_{coll}(\mathcal{F}) d^3 \mathbf{V} = 0 \quad \text{for any } \mathcal{F}. \quad (5.37)$$

- Considering a homogeneous setting, the equilibrium is a Maxwellian distribution

$$S(\mathcal{F}) = 0 \rightarrow \mathcal{F} = \mathcal{F}_M. \quad (5.38)$$

- In order to obtain identical transport properties

$$\int_{\mathbb{R}^3} \Psi S^{model}(\mathcal{F}) d^3 \mathbf{V} = \int_{\mathbb{R}^3} \Psi S_{coll}(\mathcal{F}) d^3 \mathbf{V}, \quad (5.39)$$

where $\Psi = \{V_i V_j, V_i V_j V_k, \dots, V_{i_1} \dots V_{i_M}\}$.

- Relaxation rates of the shear stress and the heat fluxes must be¹³

$$\frac{\partial \pi_{ij}}{\partial t} = -\frac{P}{\mu} \pi_{ij} \quad \text{and} \quad (5.40)$$

$$\frac{\partial q_i}{\partial t} = -\frac{2}{3} \frac{P}{\mu} q_i. \quad (5.41)$$

A Fokker-Planck model for dense gases

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Homogeneous relaxation rates of Enskog equation

- Let us simplify Enskog operator using the decomposition

$$S^{\text{Enskog}} = Y(\mathbf{x})S^{\text{Boltz}} + S_{\phi} \quad (6.1)$$

where S_{ϕ} includes all derivative of \mathcal{F} and Y in \mathbf{x} .

- Relaxation rates of shear stress and heat fluxes then become

$$\frac{\partial \pi_{ij}}{\partial t} = -Y \frac{p}{\mu^{\text{kin}}} \pi_{ij} \quad (6.2)$$

$$\text{and} \quad \frac{\partial q_i}{\partial t} = -Y \frac{2}{3} \frac{p}{\mu^{\text{kin}}} q_i, \quad (6.3)$$

- Drift and diffusion coefficients of cubic model of \mathbf{A} must satisfy this relaxation rates for dense gases.
- Spatial dependence of Enskog operator needs to be modeled.

Conservation equations of Enskog equation

Taking velocity moments $\psi \in \{1, V_j, V_j V_j/2\}$ of S^{Ensk}

$$J = \int_{\mathbb{R}^3} \psi S^{\text{Ensk}} d^3 \mathbf{V}. \quad (6.4)$$

Deploying Taylor expansion near \mathbf{x} for \mathcal{F} and Y

$$J = J_0 + J_1 + J_2 + \dots \quad (6.5)$$

where for $Y = Y(\mathbf{x})$, $\mathcal{F} = \mathcal{F}(\mathbf{V}^*, \mathbf{x})$ and $\mathcal{F}_1 = \mathcal{F}(\mathbf{V}_1^*, \mathbf{x})$

$$J_0 = 0, \quad (6.6)$$

$$J_1 = -\frac{\partial}{\partial x_i} \left[\frac{\sigma}{2} \int \int \int \int (\psi^* - \psi) Y \mathcal{F} \mathcal{F}_1 k_i g \hat{b} d \hat{b} d \hat{e} d^3 \mathbf{V}_1 d^3 \mathbf{V} \right], \quad (6.7)$$

$$J_2 = -\frac{\partial}{\partial x_i} \left[\frac{\sigma^2}{4} \int \int \int \int (\psi^* - \psi) Y \mathcal{F} \mathcal{F}_1 \frac{\partial}{\partial x_j} \left(\ln \frac{\mathcal{F}}{\mathcal{F}_1} \right) k_i k_j g \hat{b} d \hat{b} d \hat{e} d^3 \mathbf{V}_1 d^3 \mathbf{V} \right]. \quad (6.8)$$

Conservation equations of Enskog equation

- Taking velocity moment $\psi \in \{1, V_j, V_j V_j/2\}$ of expanded Enskog equation leads to

$$\int_{\mathbb{R}^3} \psi \left(\frac{\partial \mathcal{F}}{\partial t} + V_i \frac{\partial \mathcal{F}}{\partial x_i} \right) d^3 \mathbf{V} = - \frac{\partial \Psi_i^\phi}{\partial x_i}. \quad (6.9)$$

By keeping only first derivatives in Taylor expansion, one can show

$$\begin{aligned} \Psi_i^\phi = & \frac{Y\sigma}{2} \int \int \int \int (\psi^* - \psi) \mathcal{F} \mathcal{F}_1 g \hat{b} d \hat{b} d \hat{e} d^3 \mathbf{V}_1 d^3 \mathbf{V} \\ & + \frac{Y\sigma^2}{4} \int \int \int \int (\psi^* - \psi) k_i \mathcal{F} \mathcal{F}_1 \frac{\partial}{\partial x_i} \ln\left(\frac{\mathcal{F}}{\mathcal{F}_1}\right) g \hat{b} d \hat{b} d \hat{e} d^3 \mathbf{V}_1 d^3 \mathbf{V}. \end{aligned} \quad (6.10)$$

- Unlike Boltzmann, moments of Enskog operator does not vanish!
This contribution is called **Collisional Transfer**.

- Ψ_i^ϕ is approximated by Chapman and Cowling¹⁴
 - Ignoring Higher order terms.
 - $\partial_x \ln(\mathcal{F}/\mathcal{F}_1) \approx \partial_x \ln(\mathcal{F}^0/\mathcal{F}_1^0)$, where \mathcal{F}^0 is the Maxwellllian VDF.

Mass Conservation:

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_j} (\rho U_j) = 0. \quad (6.11)$$

Momentum Conservation:

$$\frac{\partial}{\partial t} (\rho U_i) + \frac{\partial}{\partial x_j} (\rho U_i U_j + \pi_{ij}^{tot} + p^{tot} \delta_{ij}) = 0. \quad (6.12)$$

Energy Conservation:

$$\frac{\partial E}{\partial t} + \frac{\partial}{\partial x_i} (E U_i + q_i^{tot} + p^{tot} \delta_{ik} U_k + \pi_{ik}^{tot} U_k) = 0, \quad (6.13)$$

where $E = \rho c_v T + \frac{1}{2} \rho U_k U_k$ and $c_v = 3k/(2m)$.

¹⁴ see Chapman and Cowling (1953) [7]

- Therefore, total pressure tensor and heat fluxes can be derived

$$p^{\text{tot}} = nkT(1 + nbY) - w \frac{\partial U_k}{\partial x_k}, \quad (6.14)$$

$$\pi_{ij}^{\text{tot}} = (1 + 2nbY/5)\pi_{ij} - (5w/6) \frac{\partial U_{\langle i}}{\partial x_{j \rangle}} \quad (6.15)$$

and

$$q_i^{\text{tot}} = (1 + 3nbY/5)q_i - c_v w \frac{\partial T}{\partial x_i}. \quad (6.16)$$

with $w = (nb)^2 Y \sqrt{mkT} / (\pi^{3/2} \sigma^2)$ being bulk effect.

- We use these expressions to correct pressure tensor and heat fluxes in FP of dense gases.

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- To guarantee relaxation rates of Enskog operator

$$\frac{\partial \pi_{ij}}{\partial t} = -Y \frac{p}{\mu} \pi_{ij} \quad \text{and} \quad (6.17)$$

$$\frac{\partial q_i}{\partial t} = -Y \frac{2}{3} \frac{p}{\mu} q_i, \quad (6.18)$$

Cubic drift **A** for dense gas should now satisfy

$$\rho \langle A_i M'_j + A_j M'_i + D^2 \delta_{ij} \rangle = -Y \frac{p}{\mu} \pi_{ij} \quad \text{and} \quad (6.19)$$

$$\rho \langle A_i M'_j M'_j + 2 A_j M'_j M'_i \rangle = -Y \frac{2}{3} \frac{p}{\mu} q_i. \quad (6.20)$$

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- Collisional transfer promotes idea of extra streaming

$$\frac{\partial \mathcal{F}}{\partial t} + \frac{\partial(\mathcal{F}V_i)}{\partial x_i} = -\frac{\partial(\mathcal{F}A_i)}{\partial V_i} + \frac{1}{2} \frac{\partial^2(D^2\mathcal{F})}{\partial V_j \partial V_j} - \frac{\partial(\mathcal{F}\hat{A}_i)}{\partial x_i}. \quad (6.21)$$

- What is $\hat{\mathbf{A}}$?

Answer: $\hat{\mathbf{A}}$ is a spatial drift which should be set such that moments of FP matches moments of Enskog, i.e. provides correction to total pressure tensor and heat fluxes.

- In this study, we proposed a linear and a cubic model for $\hat{\mathbf{A}}$.

- Consider the linear ansatz $\hat{\mathbf{A}}$

$$\hat{A}_i = \alpha v'_i . \quad (6.22)$$

- Conservation of mass:*

$$\frac{\partial \rho}{\partial t} + \frac{\partial(\rho U_i)}{\partial x_i} = 0 . \quad (6.23)$$

- Conservation of momentum:*

$$\frac{\partial(\rho U_i)}{\partial t} + \frac{\partial}{\partial x_j}(\rho U_i U_j + \pi_{ij} + p\delta_{ij}) + \frac{\partial}{\partial x_j} \int_{\mathbb{R}^3} \hat{A}_j V_i \mathcal{F} d^3\mathbf{V} = 0 . \quad (6.24)$$

- Total pressure p^{tot} of Enskog equation can be achieved by setting

$$\alpha = nbY - \frac{w}{nkT} \frac{\partial U_i}{\partial x_i} . \quad (6.25)$$

- Consider a cubic model for $\hat{\mathbf{A}}$

$$\begin{aligned}\hat{A}_i = & \hat{c}_{ij}v'_j + \hat{\gamma}_i \left(v'_j v'_j - \frac{3kT}{m} \right) \\ & + \hat{\Lambda} \left(v'_i v'_j v'_j - \frac{2q_i}{\rho} \right)\end{aligned}\quad (6.26)$$

where quadratic term is used to set total heat flux and cubic term with $\hat{\Lambda} = -\epsilon n b Y / (kT/m)$ is set to avoid instabilities of SDEs¹⁵.

- Conservation of mass

$$\frac{\partial \rho}{\partial t} + \frac{\partial(\rho U_i)}{\partial x_i} = 0 . \quad (6.27)$$

¹⁵ see Risken (1989) [20].

Cubic DFP: conservation of momentum

- First velocity moment of DFP leads to

$$\begin{aligned} \frac{\partial}{\partial t}(\rho U_i) + \frac{\partial}{\partial x_j}(\rho U_i U_j) + \frac{\partial}{\partial x_j}(\pi_{ij} + p\delta_{ij}) \\ + \frac{\partial}{\partial x_j} \left(\hat{c}_{jk}\pi_{ik} + \hat{c}_{ji}p + 2\hat{\gamma}_j q_i + \rho \hat{\Lambda} u_{ij}^{(2)} \right) = 0. \end{aligned} \quad (6.28)$$

Coefficients of spatial drift $\hat{\mathbf{c}}$ and $\hat{\gamma}$ are set to obtain total pressure and stress tensor of Enskog equation

$$\begin{aligned} \hat{c}_{jk}\pi_{ik} + \hat{c}_{ji}p + 2\hat{\gamma}_j q_i = -\rho \hat{\Lambda} u_{ij}^{(2)} \\ + nbY(p\delta_{ij} + 2/5\pi_{ij}) - w \left(\frac{\partial U_k}{\partial x_k} \delta_{ij} + \frac{5}{6} \frac{\partial U_{\langle i}}{\partial x_{j\rangle}} \right). \end{aligned} \quad (6.29)$$

- Second velocity moment of DFP provides

$$\begin{aligned} \frac{\partial E}{\partial t} &+ \frac{\partial}{\partial x_i} (EU_i + q_i + p\delta_{ik}U_k + \pi_{ik}U_k) \\ &+ \frac{1}{2} \frac{\partial}{\partial x_i} \int_{\mathbb{R}^3} \hat{A}_i V_k V_k \mathcal{F} d^3\mathbf{V} = 0. \end{aligned} \quad (6.30)$$

Substituting $\hat{\mathbf{A}}$, one can set heat fluxes of DFP to match \mathbf{q}^{tot}

$$\begin{aligned} \hat{c}_{ij}q_j &+ \frac{1}{2}\rho\hat{\gamma}_i \left(u^{(4)} - (u^{(2)})^2 \right) \\ &= \frac{3}{5}nbYq_i - wc_v \frac{\partial T}{\partial x_i} - \frac{1}{2}\rho\hat{\Lambda} \left(u_i^{(4)} - u_i^{(2)}u^{(2)} \right). \end{aligned} \quad (6.31)$$

- From momentum conservation

$$\begin{aligned} \hat{c}_{jk}\pi_{ik} + \hat{c}_{ji}p + 2\hat{\gamma}_j q_i = & -\rho\hat{\Lambda}u_{ij}^{(2)} \\ & + nbY(p\delta_{ij} + 2/5\pi_{ij}) - w \left(\frac{\partial U_k}{\partial x_k} \delta_{ij} + \frac{5}{6} \frac{\partial U_{\langle i}}{\partial x_{j\rangle}} \right). \end{aligned} \quad (6.32)$$

- From energy conservation:

$$\begin{aligned} \hat{c}_{ij}q_j + \frac{1}{2}\rho\hat{\gamma}_i \left(u^{(4)} - (u^{(2)})^2 \right) \\ = \frac{3}{5}nbYq_i - wc_v \frac{\partial T}{\partial x_i} - \frac{1}{2}\rho\hat{\Lambda} \left(u_i^{(4)} - u_i^{(2)}u^{(2)} \right). \end{aligned} \quad (6.33)$$

- Following notation was used in the formulations.

$$u_{i_1 \dots i_n}^{(k)} = \frac{1}{\rho} \int_{\mathbb{R}^3} |\mathbf{v}'|^k v'_{i_1} v'_{i_2} \dots v'_{i_n} \mathcal{F} d^3 \mathbf{V}. \quad (6.34)$$

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Using Itô calculus, equivalent Itô process of DFP is

$$d\mathbf{p} = \tilde{\mathbf{A}}dt + \boldsymbol{\lambda}d\mathbf{W}, \quad (6.35)$$

where \mathbf{W} is a Wiener process and

$$\mathbf{p} = \begin{pmatrix} M_1 \\ M_2 \\ M_3 \\ X_1 \\ X_2 \\ X_3 \end{pmatrix}, \quad \boldsymbol{\lambda} = \begin{pmatrix} D & 0 & 0 & 0 & 0 & 0 \\ 0 & D & 0 & 0 & 0 & 0 \\ 0 & 0 & D & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \quad \text{and} \quad \tilde{\mathbf{A}} = \begin{pmatrix} A_1 \\ A_2 \\ A_3 \\ M_1 + \hat{A}_1 \\ M_2 + \hat{A}_2 \\ M_3 + \hat{A}_3 \end{pmatrix}. \quad (6.36)$$

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Numerical Scheme

Explicit scheme for velocity update¹⁶, and Euler method for position update are employed as in

$$\begin{aligned} M_i^{n+1} = & U_i^n + \alpha_{cell} \left(M_i'^n e^{-\Delta t Y / \tau} + c_{ik} M_k'^n + \gamma_i (M_k'^n M_k'^n - 3kT/m) \right. \\ & \left. + \Lambda (M_i'^n M_j'^n M_j'^n - \langle M_i'^n M_j'^n M_j'^n \rangle) + \sqrt{\frac{2kTY}{\tau m}} \xi_i \right) \text{ and} \end{aligned} \quad (6.37)$$

$$\begin{aligned} X_i^{n+1} = & X_i^n + M_i^n \Delta t + \left(\hat{c}_{ij} M_j'^n + \hat{\gamma} (M_j'^n M_j'^n - 3kT/m) \right. \\ & \left. + \hat{\Lambda} (M_i'^n M_j'^n M_j'^n - \langle M_i'^n M_j'^n M_j'^n \rangle) \right) \Delta t. \end{aligned} \quad (6.38)$$

α_{cell} makes sure that kinetic energy in each cell is conserved,

$$\alpha_{cell} = \frac{\langle M_k'^n M_k'^n \rangle}{\langle M_k'^{n+1} M_k'^{n+1} \rangle}. \quad (6.39)$$

¹⁶ similar to Gorji and Jenny (2014) [21].

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- Consider a gas contained in a box with iso-thermal walls that can be moved. Velocity of particles hitting the walls in x_2 are set to the velocity of equilibrium distribution on the face¹⁷, i.e.

$$M_1 = \sqrt{\frac{k_b T_w}{m}} \mathcal{N}(0, 1) \pm U_w, \quad (7.1)$$

$$M_2 = \pm \sqrt{\frac{2k_b T_w}{m}} \sqrt{-\ln(\mathcal{R}(0, 1))} \text{ and} \quad (7.2)$$

$$M_3 = \sqrt{\frac{k_b T_w}{m}} \mathcal{N}(0, 1). \quad (7.3)$$

¹⁷ see Bird (1994) [22].

- In all simulations, Argon is used with¹⁸

μ [$kg.m^{-1}.s^{-1}$]	ω [-]	σ [m]	m [kg]	κ [$W.m^{-1}.K^{-1}$]
2.117×10^{-5}	0.5	3.628×10^{-10}	6.633×10^{-26}	0.01625

- Time step is picked based on CFL condition¹⁹

$$\Delta t = 0.05 \frac{\min(\lambda, L/n_c)}{\max(U_w, U_{th})} \quad (7.4)$$

for DSMC's based methods and

$$\Delta t = 0.05 \frac{L/n_c}{\max(U_w, U_{th})} \quad (7.5)$$

for FP based methods.

¹⁸ see Bird (1963) [22].

¹⁹ see Gorji and Jenny (2015) [23].

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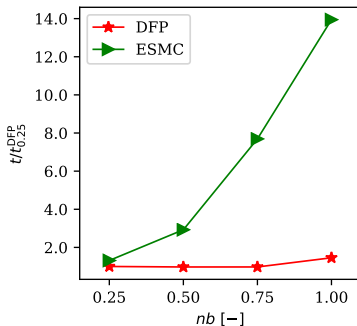
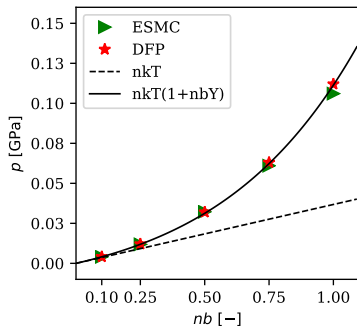
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Equilibrium Pressure

- Iso-thermal constant walls with $T_w = 273 \text{ K}$.
- Pressure can be calculated based on its fundamental definition

$$p = \frac{1}{At^f} \left(\sum_{t=0}^{t^f} \sum_{j=1}^{N_c} \Delta(mM_j) \right). \quad (7.6)$$

Dashed and solid lines are $p = nkT$ and $p = nkT(1 + nbY)$.



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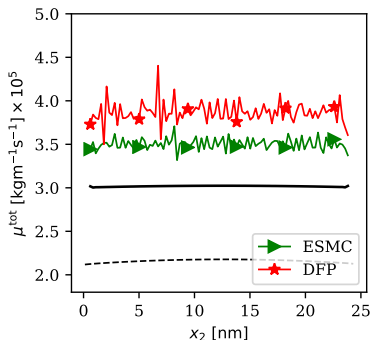
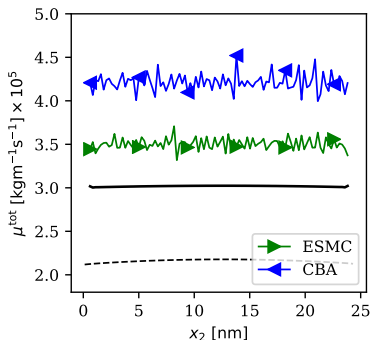
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Couette flow

- Iso-thermal walls at $T = 273 \text{ K}$ are moved $U_w = (\pm 150, 0, 0)^T \text{ [m/s]}$.
- Here, $Kn = 0.01$ and $nb = 0.5$.
- Convergence studies on the spatial refinement lead us to 100 computational cells in x_2 . 1000 particles per cell are employed.
- Solid lines $\mu_0^{\text{tot}} = \mu_0^{\text{kin}}(1 + 2n_0bY_0/5)^2/Y_0 + 3w_0/5$ and dashed line indicates μ^{kin} .



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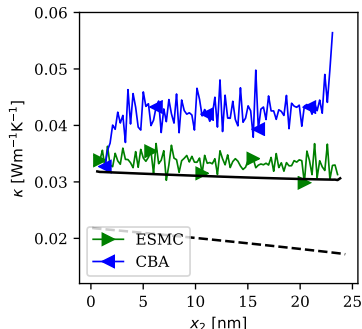
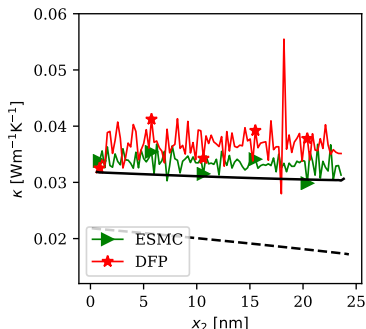
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Fourier flow

- Iso-thermal constant walls with $T_{w1} = 300\text{ K}$ and $T_{w2} = 500\text{ K}$.
- Here, $Kn = 0.01$ and $nb = 0.5$.
- Convergence studies gives us 100 cells in x_2 .
- Solid lines $\kappa_0^{\text{tot}} = \kappa_0^{\text{kin}}(1 + 3n_0bY_0/5)^2/Y_0 + w_0c_v$ and dashed line indicates κ_0^{kin} .



- We proposed a Fokker-Planck model suitable for dense gas.
- Dense gas effects were captured by introducing a spatial drift term.
- Several examples showed the accuracy of model in capturing total pressure, shear stress and heat fluxes.

- Hard Sphere (what we assumed here according to Enskog operator) is not so accurate representation of force field in very dense gases or liquids. A collision operator based on more realistic molecular potentials, such as Lennard-Jones potential, is needed.
- More accurate time integration scheme can let us increase time step.
- Idea of extra streaming might provide a framework for modeling incompressible constraint with Fokker-Planck.

Thanks for your attention.
Any questions?

Measurement of gradient

$$\langle \mathbf{Q} \rangle = \frac{\sum_{j=1}^{N_c} \mathbf{Q}_j}{N_c} . \quad (8.1)$$

$$\frac{\partial Q_i}{\partial x_j} \approx \frac{\int \frac{\partial Q_i}{\partial x_j} dV}{\int dV} = \frac{\oint Q_i n_j dA}{\Delta V} . \quad (8.2)$$

$$\langle Q_i \rangle_f = \frac{\sum_{j=1}^{N_c} Q_i^j \delta t^j}{\sum_{j=1}^{N_c} \delta t^j} = \frac{\sum_{j=1}^{N_c} Q_i^j \frac{\delta x_i^j}{M_i^j}}{\sum_{j=1}^{N_c} \frac{\delta x_i^j}{M_i^j}} . \quad (8.3)$$